Influence of the rough surface and speed of crankpin bearing on the power of the engine

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Abstract. To fully evaluate the influence of the rough surface ($\sigma$) and speed ($\omega$) of the crankpin bearing on the engine power, a combination model of the slider crank mechanism and crankpin bearing’s lubrication is established to calculate the mathematical equations for the simulation. Three indexes of the bearing-capacity ($W$), friction-force ($F$), and friction-coeficient ($\mu$) are used to evaluate the influence of the change of the crankpin bearing’s speed and rough surface on the engine’s power. The study shows that increasing $\omega$ not only effectively reduces the load capacity of the crankpin bearing but also increases the $F$ and $\mu$ in the engine’s crankpin bearing, thereby directly reducing the engine’s power. Besides, the reduction of $\omega$ also reduces the bearing-capacity of the crankpin bearing. To optimize the engine’s power, the engine’s speed should be maintained at 2000 r/min to improve the engine’s power. In addition, under the effect of the rough surface of the crankpin bearing, the $W$ of the crankpin bearing is insignificantly affected by the change of the rough surface while both the $F$ and $\mu$ are greatly affected. In particular, the maximum $F$ at $\sigma = 8$ $\mu$m and $\sigma = 10$ $\mu$m is increased by 68.3 % and 77.7 % in comparison with the maximum $F$ at minimum value of $\sigma = 2$ $\mu$m, respectively. Therefore, in the design of the engine, the rough surface of the crankpin bearing should be reduced to improve the engine’s power. Additionally, the design parameters of the crankpin bearings should also be optimized to further improve the engine’s power.

Keywords: engine power, crankpin bearing, lubrication models, engine speed, rough surface.

1. Introduction

Given greater demands to reduce environmental pollution of automobiles, technologies that can reduce the friction forces to enhance the internal combustion engine’s power are concerning and developing [1, 2]. Studies on the influence of the various design parameters of the slider crank mechanism, the inertial mass of the piston, and the eccentricities of the cylinder center and crankshaft center of the engine have been carried out over the last few decades [3-5]. The vibrations and noises generated by the friction forces between the cylinder and piston could significantly be reduced by optimizing the structure of the slider crank mechanism. Optimization studies have also investigated the characteristics of lubrication factors, such as the friction-force ($F$) and friction-coeficient ($\mu$), between two slip/nonslip surfaces of the engine’s cylinder-piston and [2, 5-6]. Researchers have found that the engine’s friction force is strongly decreased in the case of the oil film existing on the two slip/nonslip surfaces of the engine’s cylinder-piston.

Besides, the engine’s friction force is also strongly affected by the two slip/nonslip surfaces of the engine’s crankpin bearing. The lubrication model of crankpin bearings under an external load acting on the shaft moving at high speed was previously studied to evaluate the effect of the oil film thickness ($h$) on the engine’s friction force [7-9] according to the evaluation indices of the bearing-capacity ($W$) and $F$. Results showed that the stability of $h$ is decided by the film pressure existing in the crankpin bearing. The influence of the oil film’s temperature [10], load, and radial gap [7, 12-13] on the pressure of the lubrication oil film has also been analyzed [7-8, 12]. Moreover, to improve engine power, during the manufacturing process of bearings, advanced
diagnostic methods based on machine learning technology or using neural networks have been researched and applied to detect and find faulty bearings that directly affect the durability of the bearings [14-20]. In the above studies, the scholars mainly assessed the lubrication efficiency of the crankpin bearing under the condition of a static load on a shaft moving at high speed. In actual applications, the resistance of the oil film could be affected by its shear stress generated under the crankpin bearing’s various speeds and rough surfaces between the shaft and bearing surfaces.

In addition, the dynamic load of the slider crank mechanism acting on the crankpin bearing changes quickly under various engine speeds in terms of direction and intensity when the internal combustion engine is working [3, 4]. These phenomena, to some extent, may aggravate the influence of the micro asperity contact in the mixed-lubrication regime on the tribological properties of the crankpin bearing and reduce the engine’s power when the engine’s speed is changed. Therefore, the effects of the rough surface of the crankpin bearing surfaces and the engine’s speed should be taken into account during analyses of the engine power. However, investigations on the engine power considering both the rough surface and speed of the crankpin bearing have rarely been reported.

The current study establishes a study approach by coupling the slider crank mechanism and lubrication model of the crankpin bearing to evaluate the effect of the rough surface of the crankpin bearing surfaces and the engine’s speed on the engine power. An algorithm program based on the hybrid model was developed in MATLAB to solve these issues. Three indexes of the $W$, $F$, and friction-coefficient ($\mu$) are used to evaluate the influence of the change of the crankpin bearing’s speed and rough surface on the engine’s power.

2. Slider crank mechanism’s dynamic model

Based on the actual structure of an engine, the slider crank mechanism’s dynamic model could be established as shown in Fig. 1, where $L$ and $R$ the connecting rod length and rotation radius of the crankshaft, respectively. $P$ is the combustion gas pressure acting on the piston peak. $N$ and $F_c$ are the piston forces impacting on the cylinder wall and connecting rod, respectively. $F$ is the total force of the piston. $F_{ic}$, $F_{c1}$, and $F_{c2}$ are the forces of the slider crank mechanism impacting the crankpin bearing. $W_0$ is the acting force on the crankpin bearing. $\phi$ and $\omega$ are the respective angle and angular velocity of the shaft.

The piston’s motion can be determined as:

$$z_p = L + R - R\cos\phi - L\cos\theta.$$  \hspace{1cm} (1)
With \( \lambda = R/L \), therefore, the piston’s motion and acceleration can be written as follows:

\[
\begin{align*}
z_p &= R \left( 1 - \cos \phi + \frac{\lambda}{4(1 - \cos 2\phi)} \right), \\
\dot{z}_p &= R \omega^2 (\cos \phi + \lambda \cos 2\phi)
\end{align*}
\]  
(2)

where \( \omega = \dot{\phi} = d\phi/dt \). \( m_{sc} \) and \( m_{bc} \) are assumed to be masses of small- and large-rod-ends at \( o_s \) and \( o_b \) of the connecting rod. Thus, the inertial force of small-rod-end and piston is written as:

\[
F_{ip} = -(m_{sc} + m_p)R\omega^2 (\cos \phi + \lambda \cos 2\phi)
\]  
(3)

where \( m_p \) is the piston mass.

Under the effect of the combustion gas pressure acting on the piston peak, the dynamic force of \( N \) can be determined by:

\[
\begin{align*}
N &= F \tan \theta = (F_{ip} + P) \tan \theta, \\
F_c &= \frac{F}{\cos \theta} = \frac{F_{ip} + P}{\cos \theta}.
\end{align*}
\]  
(4)

The impact of \( F_c \), which has two components of tangential and radial forces, on the CB is:

\[
F_{c1} = F_c \cos(\theta + \phi), \quad F_{c2} = F_c \sin(\theta + \phi).
\]  
(5)

Under the same angular velocity of the engine \( \omega \), the \( F_{ic} \) can be defined as:

\[
F_{ic} = -m_{bc}R\omega^2.
\]  
(6)

The bearing of the connecting rod provides a rotating motion and transmits loads between the large-rod-end and crankpin. Thus, the load of the engine’s crankpin bearing is determined by:

\[
W_0 = \sqrt{(F_{c1} + F_{ic})^2 + F_{c2}^2}.
\]  
(7)

Changes in \( W_0 \) in both direction and intensity could be applied to calculate the engine power.

3. Crankpin bearing’s lubrication model

3.1. Lubrication model in the computational region

In the engine’s working process, the \( W_0 \) always impacts the crankpin is of the crankpin bearing, and the crankpin is rotated with an angular velocity of \( \omega \) inside the bearing of the connecting rod, as shown in the same Fig. 1. Therefore, the lubrication and friction of the crankpin bearing could be evaluated by modeling the crankpin under the impact of \( W_0 \) and rotated at \( \omega \) inside the bearing as shown in Fig. 2.

In Fig. 2, \( B \) and \( r_b \) are the bearing width and radius, respectively. \( r_s \) is the shaft radius and \( r_s < r_b \); \( e \) and \( \varepsilon = e/c \) (0 < \( \varepsilon < 1 \)) are the eccentricity and eccentricity ratio between the center of the bearing and shaft, respectively; \( c = r_b - r_s \) is the crankpin bearing’s gap fully filled with the lubricant to create the hydrodynamic pressure \( p \); \( u_0 = \omega r_b \) is the velocity of the crankpin surface; \( \psi \) is the attitude angle.

The \( h \) can be determined from the crankpin bearing’s lubrication model as follows [21]:

\[
h = r_b - r_s + e \cos \phi = c(1 + \varepsilon \cos \phi).
\]  
(8)
3.2. Lubrication equations of models

Assume that the bearing surface is fixed in the $x$ direction and the $y$ direction. The shaft surface moves in the $x$ direction with the velocity $u_0$, as seen in Fig. 2. Thus, the velocity condition of the oil film in the crankpin bearing is determined by:

$$
|u|_{z=h} = u_0, \quad \text{with shaft surface},
$$
$$
|u|_{x=0} = 0, \quad \text{with bearing surface}.
$$

The density and viscosity of the oil film are assumed to be unchanged in the working process of the engine, and the influence of the inertia of the lubricant flow on the working process is negligible. Thus, the equation of the lubrication film can be described as [13, 21-23]:

$$
\frac{\partial}{\partial x} \left( \varphi_x h^3 \frac{\partial p}{\partial x} \right) + \frac{\partial}{\partial y} \left( \varphi_y h^3 \frac{\partial p}{\partial y} \right) = 6 \eta u_0 \left( \frac{\partial h}{\partial x} + \sigma \frac{\partial \varphi_x}{\partial y} \right) + 12 \eta \frac{\partial h}{\partial t}.
$$

The dimensionless form of the Reynolds equation in Eq. (10) can be written as:

$$
\beta^2 \frac{\partial}{\partial \Phi} \left( \varphi_x H^3 \frac{\partial P}{\partial \Phi} \right) + \frac{\partial}{\partial \Gamma} \left( \varphi_y H^3 \frac{\partial P}{\partial \Gamma} \right) = \Lambda_1 \left( \frac{\partial H}{\partial \Phi} + \Gamma \frac{\partial \varphi_x}{\partial \Gamma} \right) + \Lambda_2 \frac{\partial H}{\partial t},
$$

where $\Phi = x/r_b$, $Y = y/B$, $H = h/c$, $P = p/p_0$, $T = t/t_0$, $u_0 = \omega r_b$, $\Lambda_1 = 6 \eta \omega B^2 / p_0 c^2$, $\Lambda_2 = 12 \eta B^2 / t_0 p_0 c^2$, $\beta = B/r_b$, $\Gamma = \sigma / c$, $p_0 = 101325$ Pa is the standard atmospheric pressure, $\sigma$ is the rough surface of the crankpin bearing, $\eta$ is the dynamic viscosity of the oil.

The boundary conditions must be determined to calculate the $p$ over the computational domain of Eq. (11). In this study, we assume that $h$ exists over the surface of the crankpin bearing and the area of the computation domain is $\Gamma$, as plotted in Fig. 3. Where $i$ and $f$ are the respective boundary lines of the initial pressure and final pressure at the maximum position of $h$ with $\phi = 0^\circ$ and $360^\circ$. $r$ and $l$ are the respective boundary lines of the right and left pressures of the bearing at $y = 0$ and $B$.

Therefore, the boundary conditions of the oil film pressure can be written as:

$$
p|_{\phi=0^\circ} = p|_{\phi=360^\circ}, \quad p|_{y=0} = p|_{y=B} = 0.
$$

By combining Eq. (11) and Eq. (12), the $p$ and $h$ of the crankpin bearing’s oil film can be calculated.
3.3. Lubrication forces of mixed hydrodynamics of crankpin bearing

Under the impact of $W_0$ on the crankpin bearing, the $W$ generated by the film pressure $p$ in $\Gamma$ is determined by [24-25]:

$$W^2 = \left( - \iint p \cos \phi dxdy \right)^2 + \left( - \iint p \sin \phi dxdy \right)^2. \quad (13)$$

The friction force $F$ of the crankpin bearing generated from the interaction shear stress acting on the shaft in $\Gamma$ can be calculated by [12]:

$$F = \iint \tau_{is} dxdy + \iint \tau_{ac} dxdy, \quad (14)$$

where $\tau_{is}$ is the interfacial shear stress, $\tau_{ac}$ is the asperity contact stress between the two surfaces of the crankpin and bearing. They were calculated by [12]:

$$\tau_{is} = \frac{\sigma}{\tau_0} + \frac{\mu_0}{15} \frac{16\sqrt{2}\pi(\zeta \eta \sigma)^2 E^*}{\frac{F_5}{2}} \left( 4 - \frac{h}{\sigma} \right), \quad (15)$$

where $\tau_1$ and $\tau_2$ are the inter-fluid shear stress and shear stress of the fluid acting on bumpy peaks, respectively, $\tau_0$ and $\mu_0$ are the shear stress and boundary friction coefficients.

When $W$ and $F$ are obtained, the $\mu$ of the engine’s crankpin bearing can be given by [23]:

$$\mu = \frac{F}{W}. \quad (16)$$

In this study, the $W$, $F$, and $\mu$ are used as indices to evaluate the engine’s power.

4. Simulation results and analysis

The necessary parameters for simulation listed in Table 1 and the combustion gas pressure acting on the piston peak, which is obtained from the experimental data in Ref. [12], as shown in Fig. 4(a), were used for calculating the $W_0$ under various $\omega$ and analyze the engine’s lubrication and friction. The $W_0$ results have been shown in Fig. 4(b).

As shown in Fig. 4(b), the impact load is constantly varied under different $\omega$ and rotation angles. The maximum value of $W_0$ is obtained at 2000 r/min while the minimum value of $W_0$ is obtained at 6000 r/min in a range of $\phi$ from 350° to 420°. However, outside of the rotational angles of 350° to 420°, the maximum value of $W_0$ is obtained at 6000 r/min. This finding may be attributed to the influence of the change of the $\omega$ in Eq. (6). Therefore, to evaluate the effect of the engine’s speed on the lubrication and friction of the crankpin bearing, a change range of $\omega$ from 1000 r/min to 6000 r/min has been simulated in Section 4.1.
Table 1. Simulation parameters of the slider crank mechanism and crankpin bearing

<table>
<thead>
<tr>
<th>Parameters</th>
<th>Values</th>
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<th>Values</th>
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<tr>
<td>$m_{bc}$ (kg)</td>
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<td>$c$ (µm)</td>
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<tr>
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<td>$R$ (mm)</td>
<td>40</td>
<td>$\eta$ (Pa·s)</td>
<td>0.02</td>
</tr>
</tbody>
</table>

4.1. Effect of engine speed

The moving speed between the two slip/nonslip surfaces of the crankpin bearing is calculated by $u_0 = \omega r_b$. Thus, the different speeds of $\omega$ of 1000 r/min, 2000 r/min, 4000 r/min, and 6000 r/min with their $W_0$ in Fig. 4(b) are simulated and computed to evaluate the $W$, $F$, and $\mu$ of the engine’s crankpin bearing.

The simulation results of the distributions of the $p$ and $\tau$ on the surface of the crankpin bearing under different $W_0$ at 2000 r/min are shown in Figs. 5(a) and 5(b). The $p$ values are mainly distributed over the range of 90° to 180° with $B$, and the maximum $p$ at 158° is 88.8 MPa. This finding is identical to the results presented in Refs. [2, 12, 23]. The shear stress $\tau$ is also uniformly distributed along $B$. However, in the circumferential direction, the shear stress $\tau$ remarkably varies and peaks at 178°.

The distributions of the $p$ and $\tau$ at a bearing width of $B/2$ under different angular speeds of $\omega$ are illustrated in Figs. 6(a) and 6(b). The result in Fig. 6(a) indicates that the $p$ greatly depends on both the values of $W_0$ and $\omega$. The maximum and minimum pressures corresponding to $W_0$ are also obtained at 2000 r/min and 6000 r/min. Conversely, the result in Fig. 6(b) shows that the $\tau$ only depends on the angular speeds of $\omega$, the $\tau$ increases with increasing $\omega$ and vice versa.
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Fig. 6. Distributions of the $p$ and $\tau$ at a bearing width of $B/2$ under different angular speeds

From the data of the $p$ and $\tau$ at the different speeds of the engine in Figs. 6(a) and 6(b), the $W$, $F$, and $\mu$ of the engine’s crankpin bearing are computed and plotted in Figs. 7(a), 7(b), and 7(c), respectively. The $W$ shown in Fig. 7(a) is similar to $W_0$ in Fig. 4(b) under various values of $\omega$ because the pressure of the oil film varies to satisfy that $W$ is equivalent $W_0$. Fig. 7(b) reveals that the $F$ increases sharply with increasing $\omega$. Moreover, the $F$ peaks at a high $\omega$ of 6000 r/min, which means the $F$ impacting on the crankpin bearing is greatest at the speed of 6000 r/min. This result may be due to the increase in the slip speed between the shaft and bearing surface, which increases the lubrication film’s friction value. Fig. 7(c) presents the $\mu$ of the crankpin bearing. The values of $\mu$ change with the variation of $W$ and $F$ and decrease with increasing $\omega$. The results of the $W$, $F$, and $\mu$ in Figs. 7(a), 7(b), and 7(c) show that when $\omega$ is maintained at 2000 r/min, $W_0$ peaks, but both the values of $F$ and $\mu$ remain relatively small. This means that the engine’s load capacity is increased while the engine’s friction is reduced. Thus, this is also a reason that most engines should work at this speed [2, 5].
4.2. Effect of surface roughness

The change of the rough surface of the crankpin bearing with $\sigma = 2 \ \mu m$, $4 \ \mu m$, $6 \ \mu m$, $8 \ \mu m$, and $10 \ \mu m$ on the engine’s tribological properties under the same conditions of a load $W_0$ at 2000 r/min is also evaluated. The simulation results of the $p$ and $\tau$ at a bearing width of $B/2$ under different surface roughness values are shown in Figs. 8(a) and 8(b).

![Fig. 8. Distributions of the $p$ and $\tau$ at a bearing width of $B/2$ under different surface roughness values](image)

The result shows that both the $p$ and $\tau$ increase with decreasing $\sigma$ and vice versa. Thus, the surface roughness $\sigma$ can affect the tribological properties of the engine’s crankpin bearing. This finding is further analyzed by plotting the results of the tribological properties of the $W$, $F$, and $\mu$, as shown in Figs. 9(a), 9(b), and 9(c), respectively.

Both Figs. 9(a) and (b) reveal that the maximum $W$ is unremarkably affected by the $\sigma$ while
the $F$ remarkably increases with increasing $\sigma$, especially at $\sigma = 8 \, \mu m$ and $\sigma = 10 \, \mu m$. This could be explained as follows. As the height of the surface roughness increases, the probability of solid contact in the asperity contact region of the surfaces of the crankpin bearing also increases, thereby increasing the pressure and stress of the asperity contact. The calculation result of the $F$ indicates that the maximum $F$ at $\sigma = 8 \, \mu m$ and $\sigma = 10 \, \mu m$ is increased by 68.3 % and 77.7 % in comparison with the maximum $F$ at minimum value of $\sigma = 2 \, \mu m$, respectively. Thus, the resistance of the crankpin bearing may be concluded to be greatly affected by the friction force generated by the rough surface of the crankpin bearing.

An increase in surface roughness remarkably increases the contacts between the micro-convex peak and the friction generated between the solid contacts. Thus, the friction coefficient $\mu$ also increases with the $F$, as shown in Fig. 9(c). Therefore, to enhance the $W$ and reduce both the $F$ and $\mu$ to improve the engine’s power, the solid contacts between the two surfaces of the crankpin and bearing should be reduced. This means that the rough surface of the crankpin bearing should be reduced.

5. Conclusions

Increasing $\omega$ not only effectively reduces the load capacity of the crankpin bearing but also increases the friction force and friction coefficient in the engine’s crankpin bearing, thereby directly reducing the engine’s power. The simulation results show that the engine’s power can be improved better when $\omega$ is maintained at 2000 r/min.

Under the change of the rough surface of the crankpin bearing simulated and analyzed, the results show that the $W$ of the crankpin bearing is insignificantly affected by the change of the rough surface while both the $F$ and $\mu$ are greatly affected. In particular, the maximum $F$ at $\sigma = 8 \, \mu m$ and $\sigma = 10 \, \mu m$ is increased by 68.3 % and 77.7 % in comparison with the maximum $F$ at minimum value of $\sigma = 2 \, \mu m$, respectively. Thus, the rough surface of the crankpin bearing should be reduced to improve the engine’s power.

Improving the lubrication while reducing the friction of the engine is a challenging issue. Therefore, the present study not only contributes to the existing body of knowledge on the engine lubrication and friction of automotive engines but also provides an important reference for optimal design parameters to improve this engine property further.

Based on the research results, we also discovered that the design parameters of the crankpin bearings should also be optimized to further improve the engine’s power. Besides, adding microtextures to the bearing surface can also enhance the lubricating oil film and reduce contact friction generated between the two surfaces of the crankpin and bearing, thereby improving engine power. These issues can continue to be researched.

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Data availability

The datasets generated during and/or analyzed during the current study are available from the corresponding author on reasonable request.

Conflict of interest

The authors declare that they have no conflict of interest.
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