

Structural damage detection by progressive continuous wavelet transform and singular value decomposition of noisy mode shapes

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Abstract. For decades, damage identification based on structural mode shapes has been a popular research topic. While mode shapes provide valuable spatial structural information, the sensitivity to localized damage remains limited. In contrast, modal curvature exhibits high sensitivity to local damage, enabling precise damage localization. However, its susceptibility to environmental noise poses a significant limitation. To this end, a novel damage identification method is proposed by integrating continuous wavelet transform (CWT) and singular value decomposition (SVD). First, the CWT is applied to structural mode shapes for generating continuous wavelet coefficients. Subsequently, the SVD is performed on these coefficients, yielding new damage indicator termed as the singular image of continuous wavelet coefficients (SICWC). The SICWC enhances damage sensitivity and localization accuracy by suppressing noise-induced global trends in structural mode shapes. The effectiveness of proposed method is validated through numerical simulations of a cantilever beam under noisy conditions, as well as experimental detection of a cracked beam using mode shapes acquired via a scanning laser vibrometer. The results demonstrate that SICWC effectively mitigates the limitations of traditional damage detection methods based on mode shape and curvature.

Keywords: damage detection, mode shape, singular value decomposition, wavelet transform, noisy environment, scanning laser vibrometer.

1. Introduction

Structures inevitably suffer damage during the long-term operation process [1-4]. Damage detection is extensively involved in the fields of mechanics, aerospace, and civil engineering [5-8]. In particular, vibration-based damage detection using dynamic response signals is a hot topic in literature [9-15]. Beam-type structures are the most frequently occurring components among various structures [16-18]. In the past, the detection of beam damage relied on methods based on vibration frequency. However, the methods based on mode shapes have gradually attracted more attention because the ability of providing spatial information and high sensitivity to local damage [19].

The representative research on identifying beam damage through modes shapes are summarized as follows. Abdo and Hori [20] effectively located the damage region by using the rotation of mode shapes. Ismail [21] proposed a modal vibration mode regression index and successfully identified three cracks existing simultaneously in reinforced concrete beams, which has high simplicity and reliability. Rahai et al. [22] demonstrated that the measured incomplete

mode shapes also have the ability to detect structural damage in a noisy environment. Parloo et al. [23] experimentally validated a damage assessment method for detecting the damage of the I-40 highway bridge in the United States using the sensitivity of mode shapes. Ratcliffe [24] devised a method to detect the locations of damage based the measured mode shapes and experimentally verified it on beams. Kim et al. [25] adopted a damage detection method based on modal shapes to estimate and evaluate the damage of prestressed concrete beams. Shi et al. [26] proposed a more accurate and robust method to identify damage by directly using incomplete mode shapes to identify damage and verified it on planar truss structures. Qiao and Cao [27] created an AWCD-MAA method, and experimentally validated its effectiveness on a composite cantilever beam with cracks. Common studies on beam damage detection share key features: they utilize mode shape changes (e.g., rotations or deformations) to locate damage, work with incomplete or noisy measurements, and conduct experimental validation. Several methods have successfully identified multiple damage areas, while others have introduced novel algorithms to enhance accuracy and robustness.

Although the existing damage detection methods based on modal shapes have the ability to characterize the damage as described in the above-mentioned literature, they are not very sensitive to local damage [28]. Researchers have found that modal curvature can not only detect the existence of damage but is also sensitive to the location of the damage [29, 30]. Nevertheless, a notable drawback of modal curvature is that it is susceptible to measurement noise, thereby undermining the damage characteristics [31]. To address the shortcomings of damage identification methods based on modal curvature, diagnostic methods that are immune to noisy environments urgently need to be developed.

To this end, a new method is proposed here that differs from the existing methods. The proposed method focuses on producing singular images of the continuous wavelet coefficients and singular values of measured mode shapes [32-34]. The singular image of the continuous wavelet coefficients of the mode shapes, termed SICWC of the mode shapes, has the advantages of damage sensitivity and noise immunity. The effectiveness and advantages of SICWC are numerically demonstrated by comparing with conventional modal curvature results of a cracked cantilever beam. The practicability of SICWC is experimentally validated by the identification results of an aluminum beam with a small crack.

2. SVD for damage detection

2.1. Fundamental concepts

2.1.1. SVD

The SVD is a highlight of linear algebra. The SVD of a matrix X with $m \times n$ dimensions and rank r can be written as:

$$X = USV^T, \quad (1)$$

where U and V are the orthogonal matrixes with the dimension of $m \times m$ and $n \times n$. The columns of U are the left singular vectors, while the rows of V^T contain the right singular vectors. $S = \begin{bmatrix} \Sigma_r & 0 \\ 0 & 0 \end{bmatrix}$ is a $m \times n$ diagonal matrix, in which, $\Sigma_r = \text{diag}(\sigma_1, \sigma_2, \dots, \sigma_r)$. σ_i is defined as the singular values of X . A rank- k approximation of X can be defined as:

$$X^k = \sum_{i=1}^k \sigma_i u_i v_i^T, \quad (2)$$

where, $u_i v_i^T$ can be called the singular image of X corresponding to its singular value. X^k is the

rank- k approximation [35] of X , the approximation error is defined as:

$$\varepsilon^k = \|X - X^k\|_F = \sum_{i=1}^r \sigma_i^2 - \sum_{i=1}^k \sigma_i^2 = \sum_{i=k+1}^r \sigma_i^2. \quad (3)$$

Therefore, more singular values and the corresponding singular vectors can reduce the approximation error:

$$\alpha_i = \frac{\sigma_i^2}{\sum_{j=1}^r \sigma_j^2}. \quad (4)$$

The above ratio shows the weight of singular image ($u_i v_i^T$) in description of X ; that is, the importance of the singular image for X is proportional to the size of the corresponding singular value. When $i = 1$ and α_i is close to 1, the rank-1 approximation (X^1), i.e., the first singular image ($u_1 v_1^T$), is sufficiently accurate, containing almost all the information of X . Other singular images of X conserve local or partial information of X . In particular, if the X elements are noisy, we can conclude that small singular values are due to noise, and discarding them can reduce the noise level [36].

2.1.2. Wavelet

The 1D-wavelet [37] can be described as:

$$\psi_{u,s}(x) = \frac{1}{\sqrt{s}} \psi\left(\frac{x-u}{s}\right), \quad (5)$$

which should meet the following requirement:

$$\int_{-\infty}^{\infty} \frac{|\hat{\psi}(\omega)|^2}{|\omega|} d\omega < \infty, \quad (6)$$

where, s and u are the scale parameter and translation parameter, $\psi(x)$ is the mother wavelet.

2.2. Synergic regime: SICWC of WT mode shape

The new damage feature characterized by singular image of continuous wavelet coefficients of a mode shape is generated with mode shape, WT mode shape, and the proposed SICWC index.

2.2.1. Mode shape

Consider a noisy displacement mode shape W and its 2nd derivative W'' , representing the curvature mode shape. The numerical differentiation process dramatically magnifies measurement noise present in W , generating a highly distorted curvature profile where damage indicators become indistinguishable [38, 39]. Consequently, this inherent noise amplification severely limits the practical utility of curvature mode shapes for reliable damage assessment in operational conditions.

2.2.2. WT mode shape

The Mexican hat wavelet [37] is selected as:

$$g_{u,s}(x) = \frac{1}{\sqrt{s}} g\left(\frac{x-u}{s}\right), \quad (7)$$

where, x is displacement mode shape, s and u are the scale and translation parameters. This wavelet is used to convolute W as:

$$W_{u,s}^* = W \otimes g_{u,s}, \quad (8)$$

where, \otimes means the convolution, $W_{u,s}^*$ is the convolution result.

2.2.3. SICWC of WT mode shape

Implementation of the SVD on $W_{u,s}^*$ at all scale levels is expressed as:

$$W_{u,s}^* = USV^T. \quad (9)$$

From Eq. (2), $W_{u,s}^*$ can also be expressed as:

$$W_{u,s}^* = \sum_{k=1}^r \sigma_k u_k v_k^T, \quad (10)$$

where $u_k v_k^T$ is the singular image of the WT mode shape. The importance of a singular image for $W_{u,s}^*$ is proportional to the size of the singular value. σ_k is the singular value of the WT mode shape. $\sigma_k u_k v_k^T$ is defined as the SICWC of WT mode shape. The singular images can be used to retrieve damage information of the WT mode shape.

3. Numerical simulation

3.1. Numerical model

A cantilever beam with dimensions $L = 200$ mm (length), $b = 10$ mm (width), and $t = 10$ mm (thickness), is considered, as shown in Fig. 1. The beam material properties include elastic modulus, Poisson's ratio, and density of 206 GPa, 0.3, and 7860 kg/m³, respectively.

To simulate damage, a crack is introduced at the distance of 60 mm from the fixed end with a normalized damage severity $\xi = 0.15$, where $\xi = a/t$ represent the crack depth ratio (a : crack depth, t : beam thickness). For numerical modeling, the model of the beam is meshed with 2-node 1D beam-type elements using finite element analysis. The beam is modeled by 300 elements containing 301 nodes, the mode shape of the beam is achieved by numerical modal analysis.

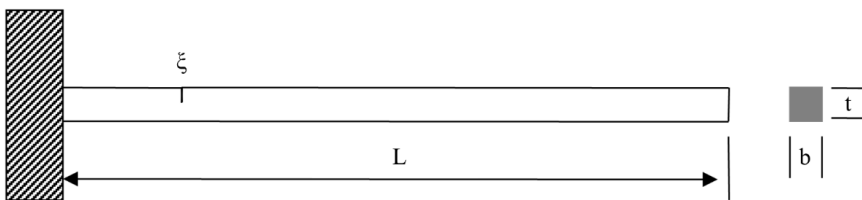


Fig. 1. Schematic diagram of the cracked cantilever beam

3.2. Identification of damage

3.2.1. Crack location

As shown in Fig. 2, the first seven mode shapes of the beam obtained numerically are used to

demonstrate the capability of the SICWC of mode shapes for identifying a crack in a noise-free environment. There are no curve of the seven mode shapes shows the damage location clearly. The variation of lower-order mode shapes is relatively gradual, exhibiting a smooth overall trend. In contrast, higher-order modes demonstrate more pronounced fluctuations. When cracks are located near the maxima or minima of the mode shapes, irregularities in the curves become observable, as exemplified by the modes VI and VII. In general, directly identifying damage locations through mode shapes proves challenging due to the inconspicuous singularity induced by the damage.

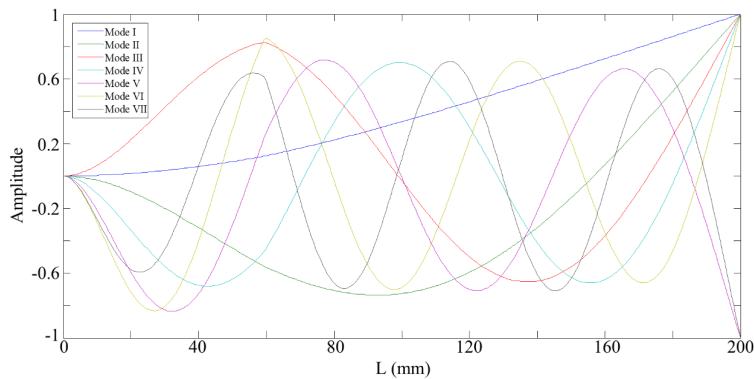


Fig. 2. The first seven mode shapes curves of the beam

The 4th mode shape is arbitrarily selected for verifying the proposed method. The 4th mode shape of the beam and its WT mode shape are shown in Fig. 3(a) and Fig. 3(b), respectively. Neither the mode shapes nor the wavelet mode shapes at different scales exhibit sensitivity to cracks. This observation indicates that directly utilizing mode shapes is insufficient for identifying structural damage.

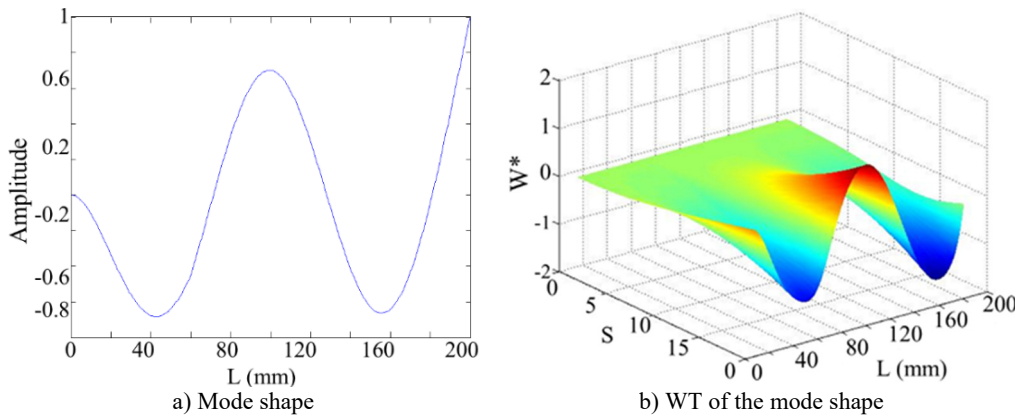


Fig. 3. The 4th order mode

When SVD is implemented on the WT mode shape, a series of singular images of continuous wavelet coefficients are obtained. The number of singular images equals to the number of singular values of the WT mode shape, and the same as the number of scales of the WT. The singular values of the beam's WT mode shape are shown in Fig. 4. It can be observed that the first singular value is significantly larger than the others, indicating that the first-order singular pattern captures more global structural information, thereby exhibiting insensitivity to localized damage. It should be noted that the ratio of the first singular value to the summation of all singular values is over 95 %, as shown below:

$$\alpha = \frac{\sigma_1}{\sum_{i=1}^r \sigma_i} = 95.27 \%. \quad (11)$$

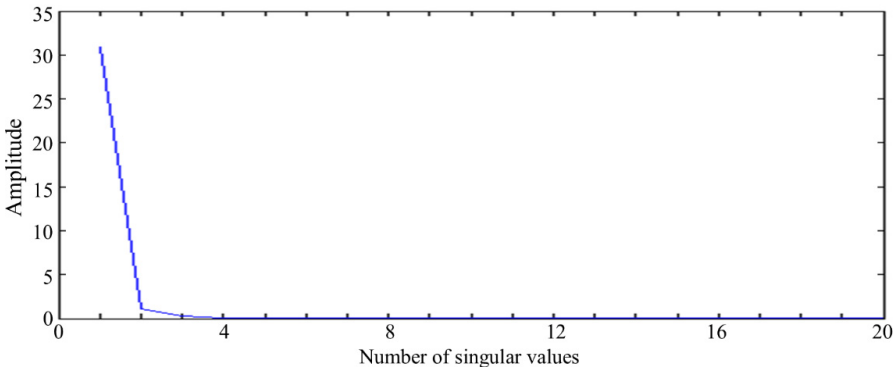


Fig. 4. Singular values of WT mode shape

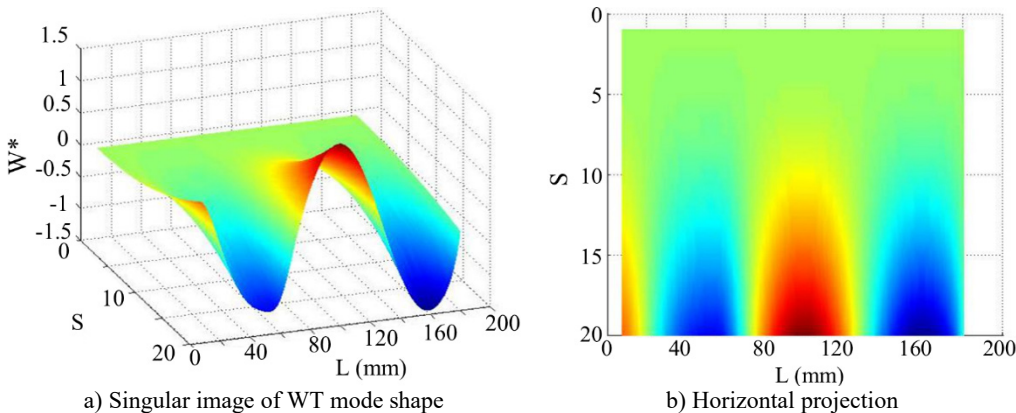


Fig. 5. The 1st order mode

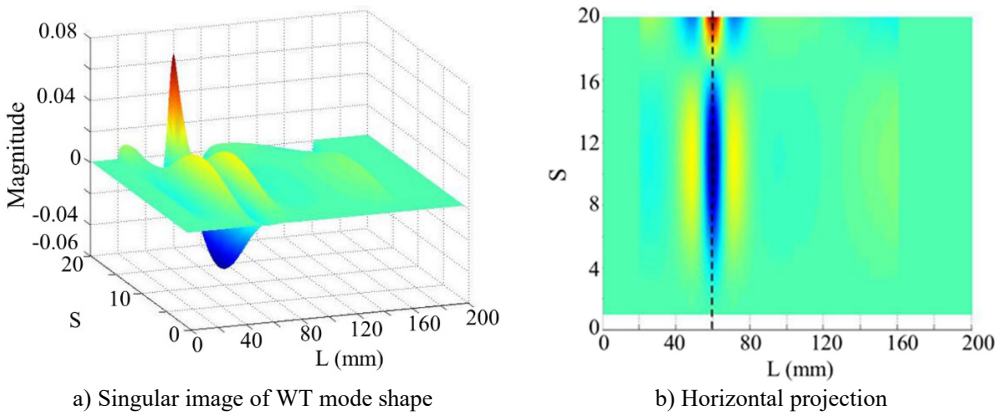


Fig. 6. The 2nd order mode

As shown in Fig. 5, the first singular image of the WT mode shape reflects most of global information of the WT mode shape, in which no damage feature can be found. It is then investigated if other singular images of the WT mode shape can reveal local damage information. As shown in Fig. 6, the 2nd singular image of the WT mode shape clearly shows the damage location at 60 mm, and the 2nd singular value is at the corner (or sharp bend) of the singular values

curve. To avoid the end-effect problem of the WT method, some points near the end of the beam are removed before the WT mode shape is computed for the SVD operation, and their values are set as zeros in the singular image of the WT mode shape. This operation is also applied to the subsequent singular images of WT mode shape.

As shown in Fig. 7, the 3rd singular image of the WT mode shape reflects damage location but with some perturbation, possibly caused by waviness in the WT mode shape or numerical errors, and the 3rd singular value is close to the corner of the singular values curve.

The 4th and 5th singular images of the WT mode shape, as shown in Figs. 8 and 9 respectively, barely show damage location because of greater perturbation. Their singular values are very small and are located on the almost horizontal part of the singular values curve.

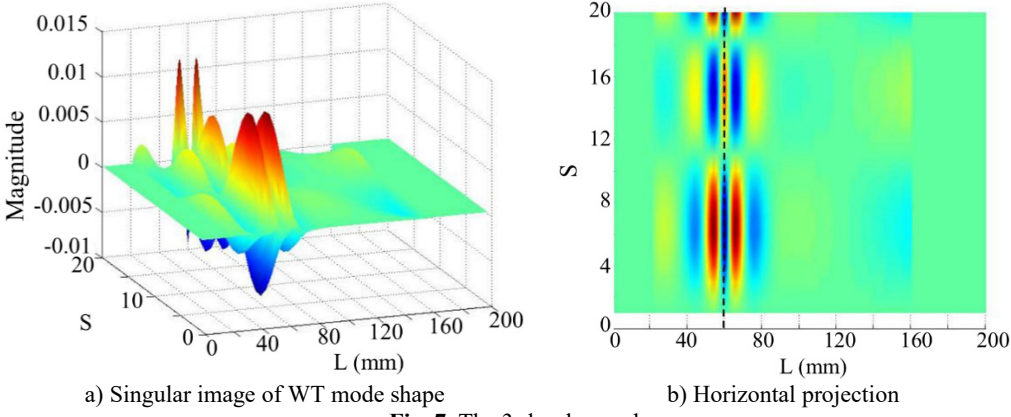


Fig. 7. The 3rd order mode

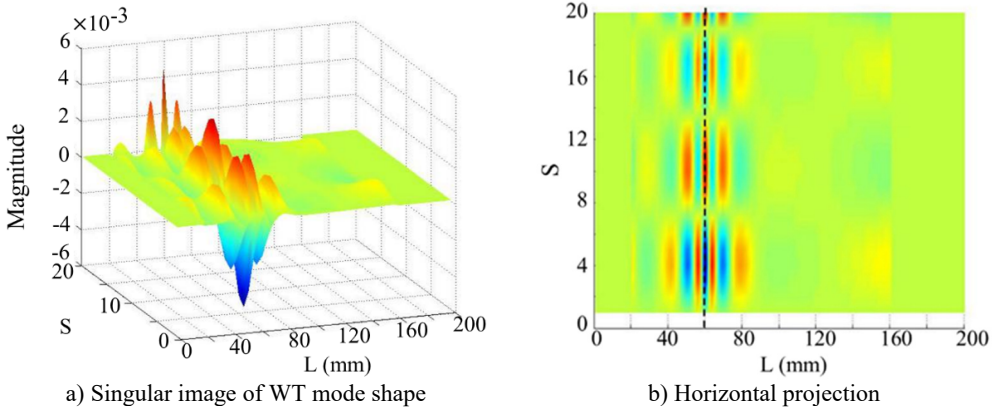


Fig. 8. The 4th order mode

The choice of the order in singular image significantly affects the outcome of damage identification. The singular images of WT mode shape correspond to the singular values in the descending part and near the sharp bend of the singular values curve can reflect most damage information. The singular images of WT mode shape corresponding to singular values in the approximately horizontal part of the singular values curve shows more error or noise perturbation than damage information. A Shannon entropy method is used for mathematical justification of the selection of these singular images. A normalized singular space of each singular image, \bar{Z} , is constructed from singular image ($Z = \sigma_k u_k v_k^T$) using the following transformation:

$$\bar{Z}_{(i,j)} = \frac{Z_{(i,j)} - \min(Z_{(i,j)})}{\max(Z_{(i,j)}) - \min(Z_{(i,j)})}. \quad (12)$$

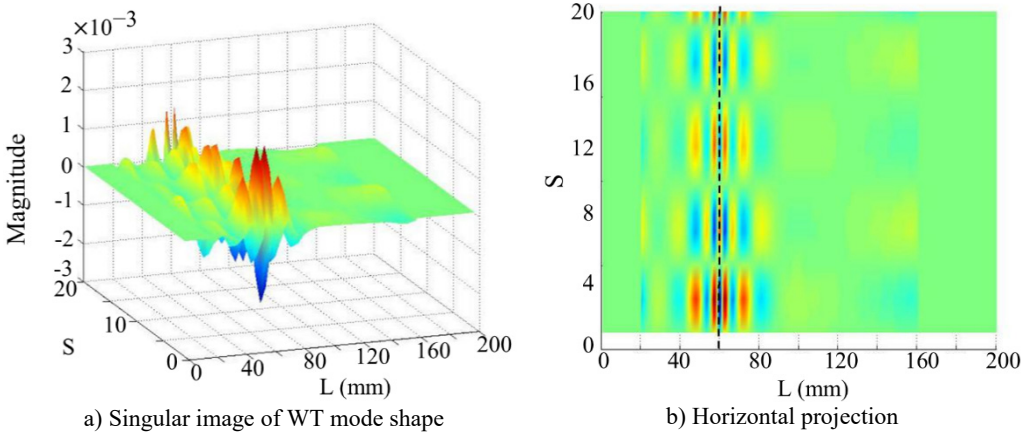


Fig. 9. The 5th order mode

The Shannon entropy is described as:

$$E(a) = - \sum_j \sum_i \bar{Z}_{(i,j)} * \log[\bar{Z}_{(i,j)}]. \quad (13)$$

When the number of singular images is varied, noted as a , a curve of $E(a)$ versus a is generated. The minimum entropy criterion is defined as:

$$a_{op} = \arg \min_k E(a), \quad (14)$$

where $\arg \min$ is:

$$\arg \min_{x \in S} f(x) = \{x \in S: f(x) = \min_{y \in S} f(y)\}. \quad (15)$$

In Eq. (14), the minimum entropy results in a_{op} inducing an optimal enhanced a singular space, in which the structural damage trait can be utmost dominant in comparison with the other singular spaces. The Shannon entropy for the 4th mode shape can be seen in Fig. 10.

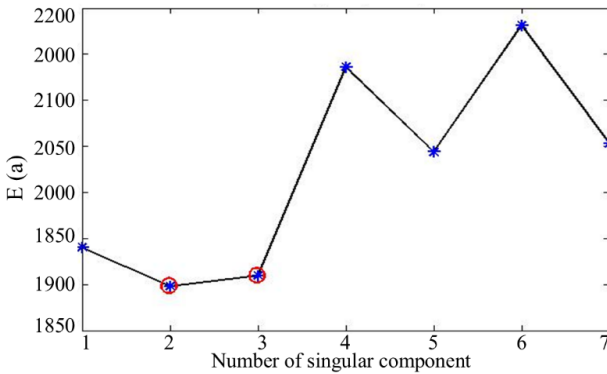


Fig. 10. The Shannon entropy measure for each singular image

The Shannon entropy values of the 2nd and 3rd singular images are notably less than that of other singular images, meaning that the damage is dominated by the 2nd and 3rd singular images. Hence, a combination of the 2nd and 3rd singular images of the WT mode shape is very effective for damage detection, as shown in Fig. 11. Obviously, damage in the beam can be clearly detected at 60 mm.

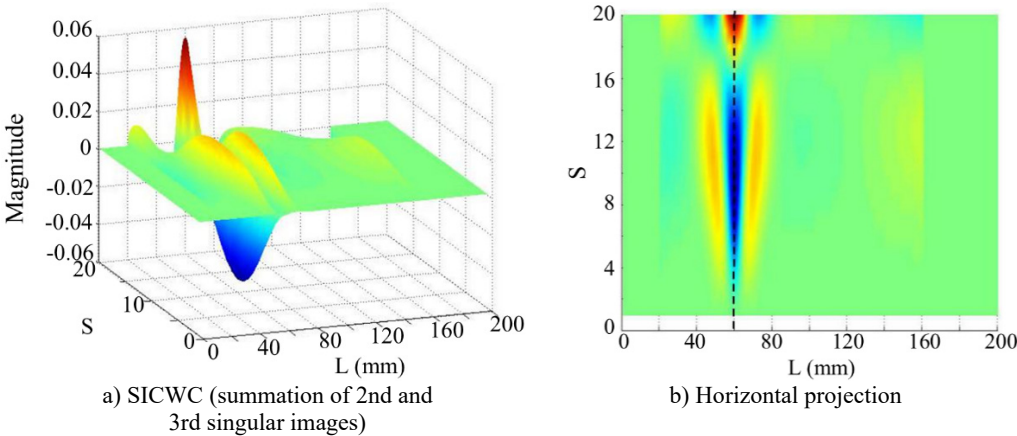


Fig. 11. The 4th order mode

The other six mode shapes of the cantilever beam, after combining the 2nd and 3rd singular images of their WT mode shape (see Figs. 12-17). The WT mode shape cannot show damage, but every SICWC of mode shape shown in these figures clearly identifies the damage location in the beam.

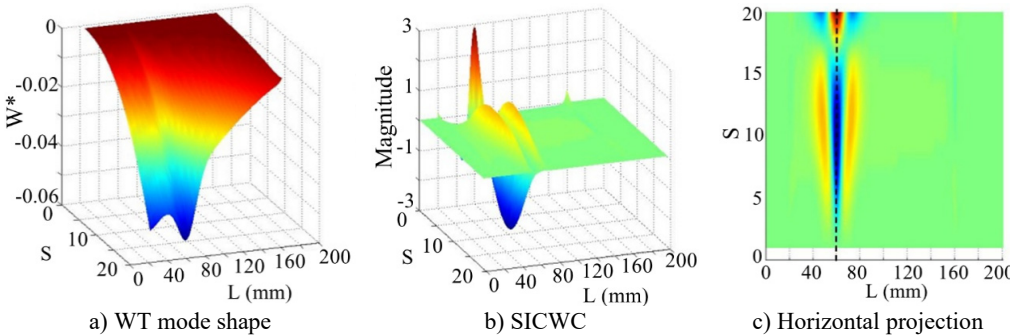


Fig. 12. The 1st order mode

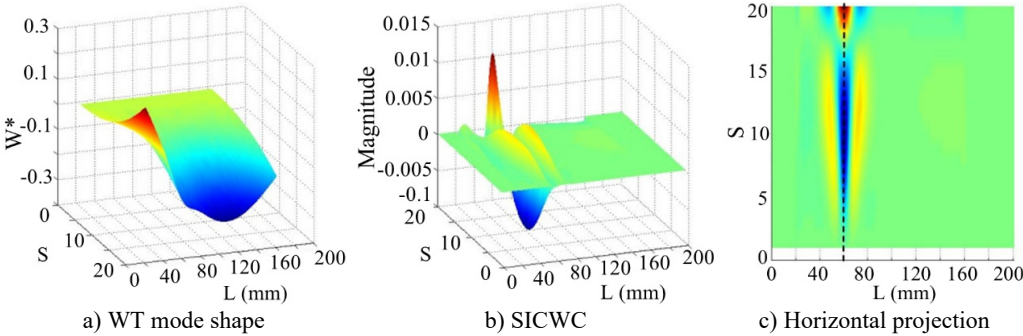


Fig. 13. The 2nd order mode

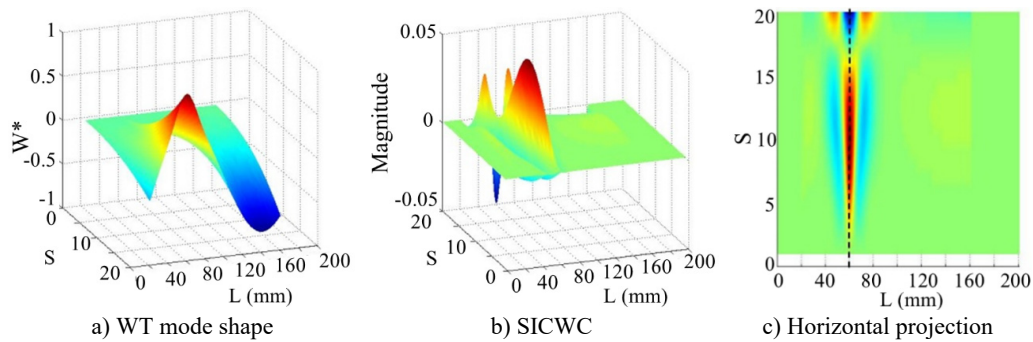


Fig. 14. The 3rd order mode

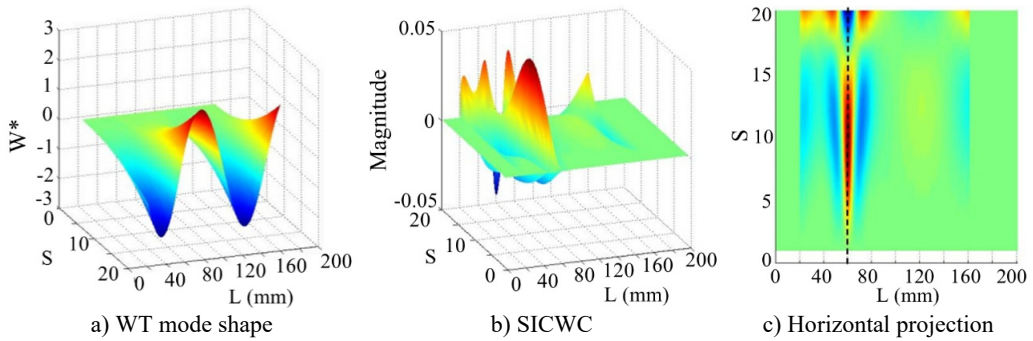


Fig. 15. The 5th order mode

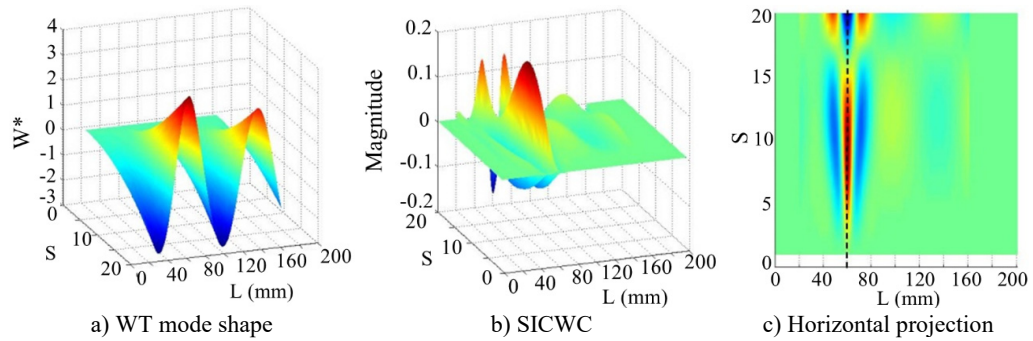


Fig. 16. The 6th order mode

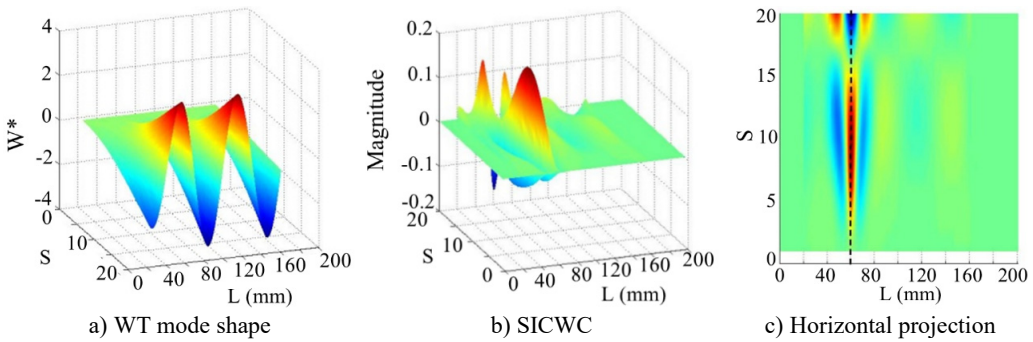


Fig. 17. The 7th order mode

The above analytical results demonstrate that: (i) both conventional and wavelet-based mode

shapes exhibit insensitivity to damage, (ii) the proposed mathematical justification of the selection of these singular images is effective, and (iii) the proposed SICWC shows high sensitivity to crack locations.

3.2.2. Crack quantification

Possibility of the SICWC of a mode shape to quantify damage is studied with crack cases, $\xi = 0.15$, $\xi = 0.2$, $\xi = 0.25$, and $\xi = 0.3$ for a crack located at 60 mm and 90 mm. For the five crack cases, the WT mode singular images generated by the five orders modes can reveal the dominant peaks caused by the cracks. With the increase of the crack depth, the amplitude of this peak increases. This peak is defined as singular peak since it is generated by singular value decomposition. It can be clearly seen from Fig. 18 that for the five crack cases with a scale of $s = 10$, two sets of ξ arranged singular peak slices appear at 60 mm and 90 mm.

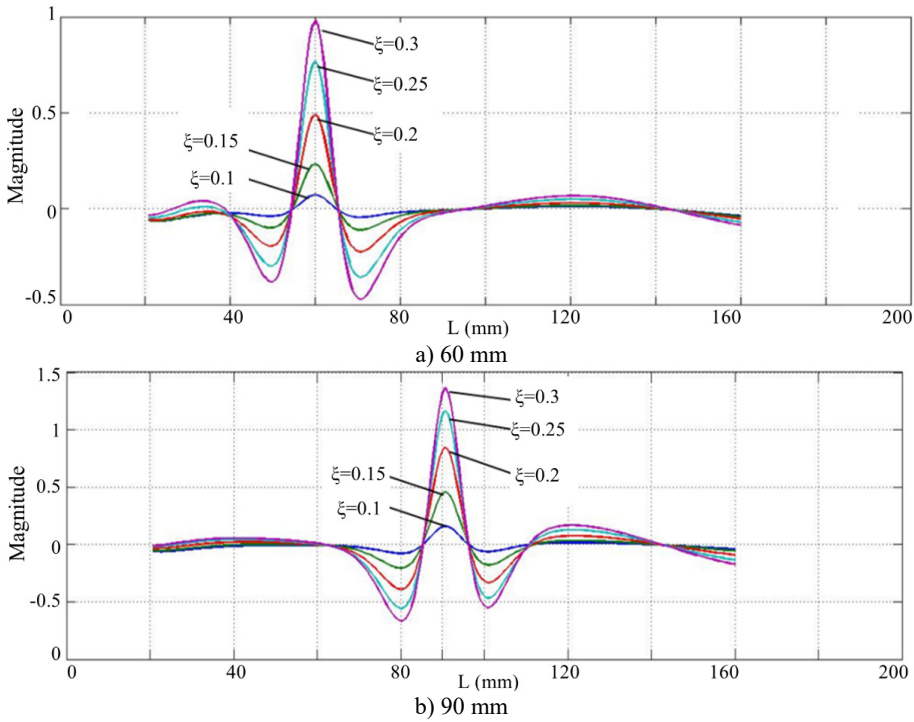


Fig. 18. Singular peaks five crack cases with different crack depth at the scale $s = 10$

In each group shown in Figs. 18(a) and (b), the crack depth influences the highest point of the singular peak. This relationship between damage severity and peak characteristics demonstrates that the mode shape's SICWC can be used to assess crack depth in structural beams. This damage characteristic is particularly advantageous for monitoring the progression of damage severity at the same location.

3.3. Noise effects on damage identification

The noise resistance of the SICWC during damage identification are investigated by incorporating white Gaussian noise to the original mode shapes. The intensity of white Gaussian noise is measured by the signal-to-noise ratio (SNR). For the cracked beam depicted in Fig. 1, the 5th mode shapes with SNR of 70 dB, 40 dB, and 30 dB are arbitrarily selected for this analysis. For comparisons, the curvature mode shapes given by the second order differentiation are also

investigated, as shown in Figs. 19(a)-24(a). In Fig. 19(a), when the SNR is 70 dB, although the damage feature can be detected at 60 mm by careful observation, the mode shape containing indiscernible noise impairs the profile of the curvature.

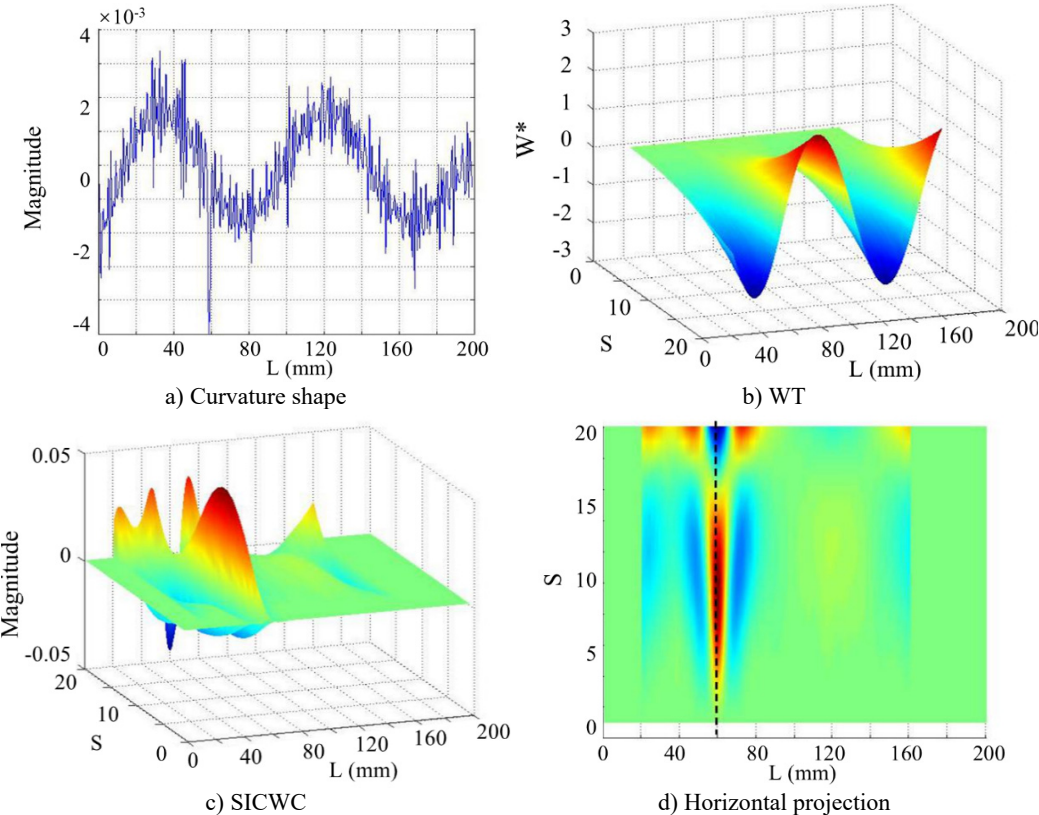


Fig. 19. The 5th order mode under SNR of 70 dB

Moreover, when the SNR of the responses reduce to 40 dB, 30 dB, and 20 dB, the shapes of the curvatures are severely disturbed. WT mode shapes are generated and plotted in Figs. 20(b)-24(b). As the scale increases, noise in each WT mode shape is significantly reduced, aiding damage detection. However, the overwhelming dominance of the global trend obscures the damage feature, making crack identification difficult. In contrast, the proposed SICWC can obviously highlight the damage location of the beam. The WT mode shapes are further treated by the SVD, producing the SICWC of WT mode shapes (see Figs. 19(c)-24(c)), and the corresponding horizontal projections (see Figs. 19(d)-24(d)). For the 5th order, when the SNR is 70 dB, the elimination of the mode shape's global trend isolates a prominent singular peak, which serves as a clear indicator of the crack's occurrence and exact position at 60 mm (Fig. 19(c) and 19(d)).

When the SNR reach 40 dB, the damage feature can be identified at 60 mm by careful observation, especially in its horizontal projection (Fig. 20(d)). When the SNR reach 30 dB, noise severely impairs the profile of the SICWC, which is incapable of showing the damage in the beam (Figs. 21(c)-(d)). Nevertheless, when higher-order mode is considered, the 7th order SICWC of the WT mode shape clearly indicates the location of the crack at 60 mm with the SNR of 30 dB, as shown in Figs. 22(c) and (d). Moreover, for the 11th mode shape incorporating SNR of 20 dB, the damage feature cannot be obviously found at 60 mm by the SICWC and its horizontal projection (see Figs. 23(c) and (d)). In Figs. 24(c) and (d), the damage location can be clearly seen

in the SICWC of the WT mode shape for the 13th mode with SNR of 20 dB. The SICWC results of different-order mode shapes under 30 dB and 20 dB conditions demonstrate that higher-order modes exhibit greater sensitivity to localized damage compared to lower-order modes.

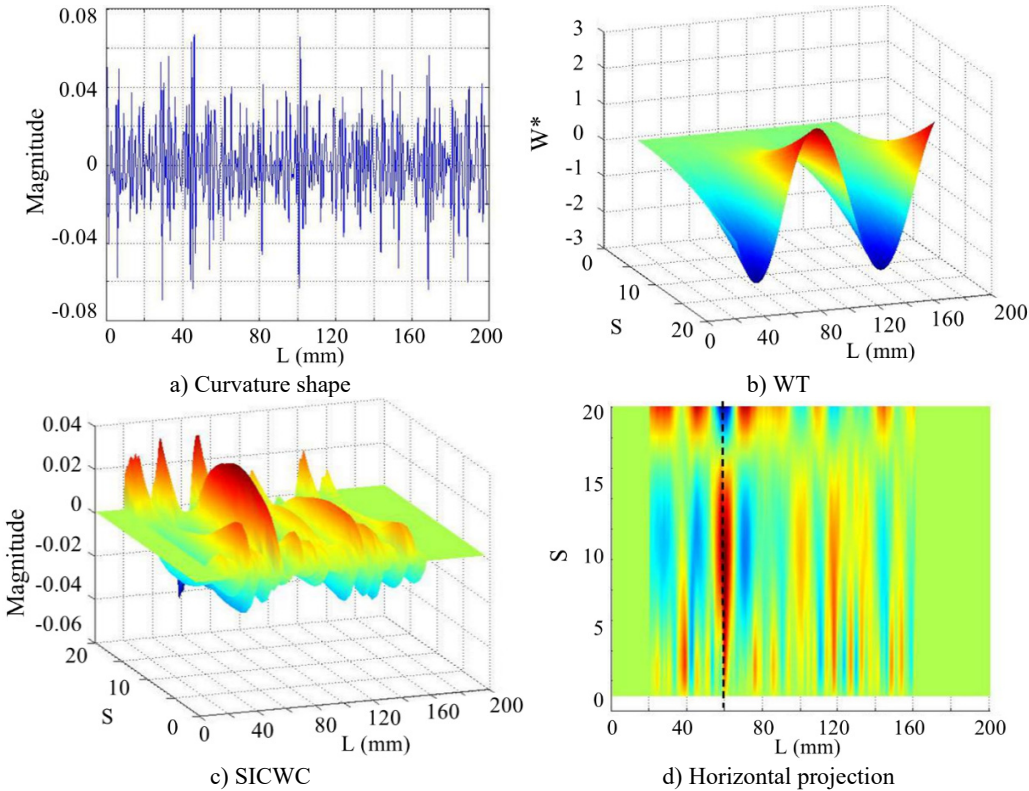
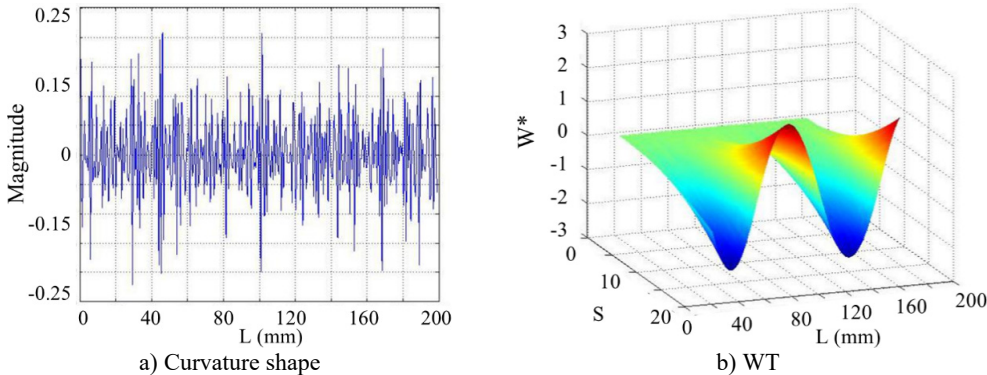


Fig. 20. The 5th order mode under SNR of 40 dB

4. Experimental validation

4.1. Layout of the experiment

As shown in Fig. 25, an aluminum cantilever beam with the length of 543 mm, width of 30 mm, and depth of 8 mm is tested. The beam is set with a crack, which has the width of 1.2 mm and the depth of 2 mm. The distance of the crack to the fixed end is 293 mm. The 10-order mode shapes of the cantilever beam are excited by a shaker and collected by a scanning laser vibrometer.



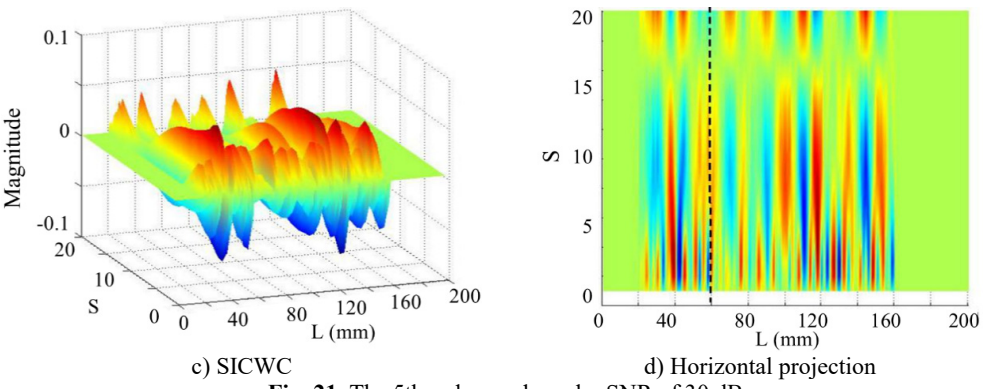


Fig. 21. The 5th order mode under SNR of 30 dB

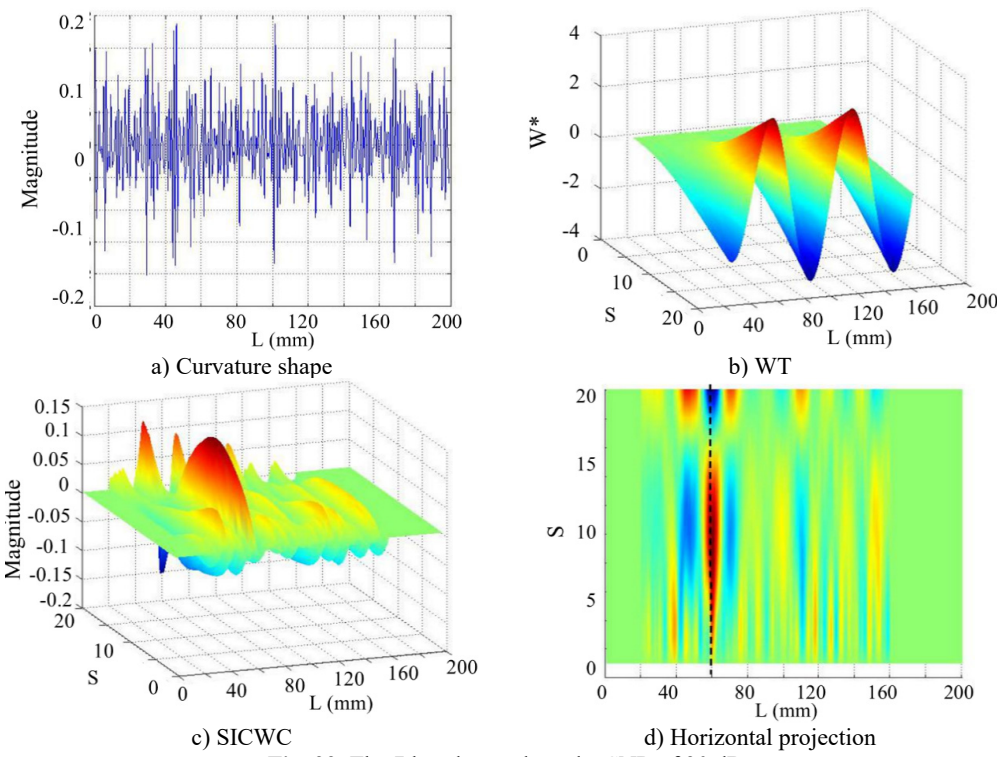
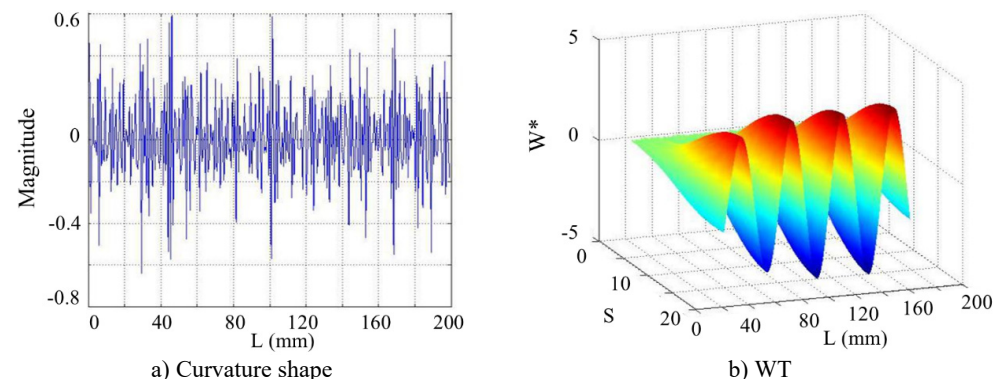
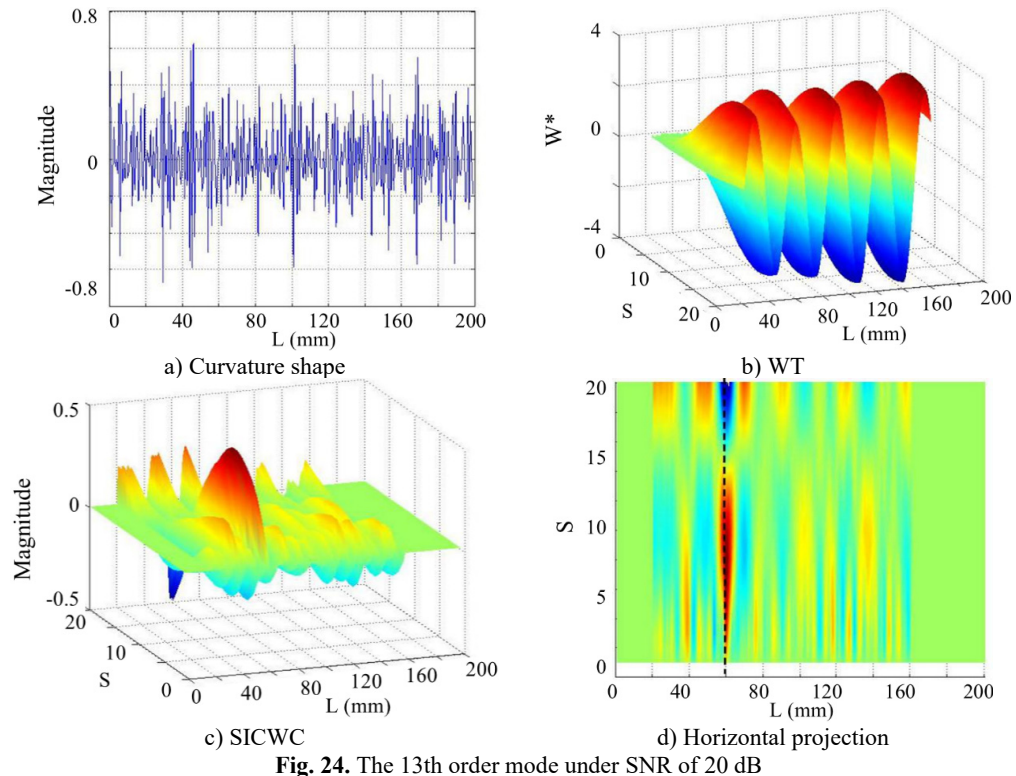
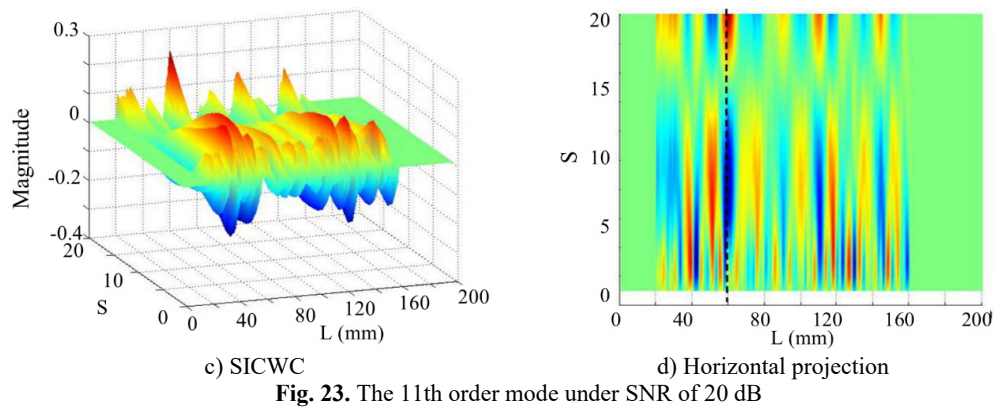


Fig. 22. The 7th order mode under SNR of 30 dB

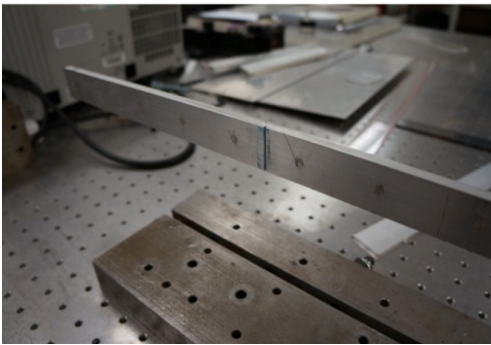




Before commencing the formal testing procedures, an extensive frequency sweep test was conducted on the cantilever beam specimen using the shaker. The excitation frequency at which the beam's response (obtained at any point on the beam via scanning laser vibrometer) exhibits significant resonance is identified as the natural frequency. Subsequently, during the formal testing, these identified natural frequencies are used to independently excite the beam one by one, while the laser vibrometer scans all measurement points sequentially to construct the mode shapes. Unlike the noise-free environment of numerical simulations, the testing of the cantilever beam specimen inherently contains noise arising from the tightness of structural connections, nonlinear effects of the shaker, surface reflectivity conditions, and measurement errors in the laser testing system.



a) Scanning laser vibrometer



b) Beam component containing a crack

Fig. 25. Experimental setup

4.2. Experimental crack identification

It should be noted that not all of the obtained 10-order mode shapes are equally sensitive to damage. Generally, lower-order mode shapes exhibit higher signal quality but lower damage sensitivity, whereas higher-order mode shapes, though more challenging to measure, demonstrate greater sensitivity to localized damage. The insensitivity of lower-order mode shapes stems from their low modal curvature, which makes damage identification difficult, while the pronounced curvature variations in higher-order mode shapes facilitate damage detection. However, acquiring higher-order mode shapes remains challenging due to their low mode energy and susceptibility to noise interference, which precisely motivates the proposed SICWC indicator in this study.

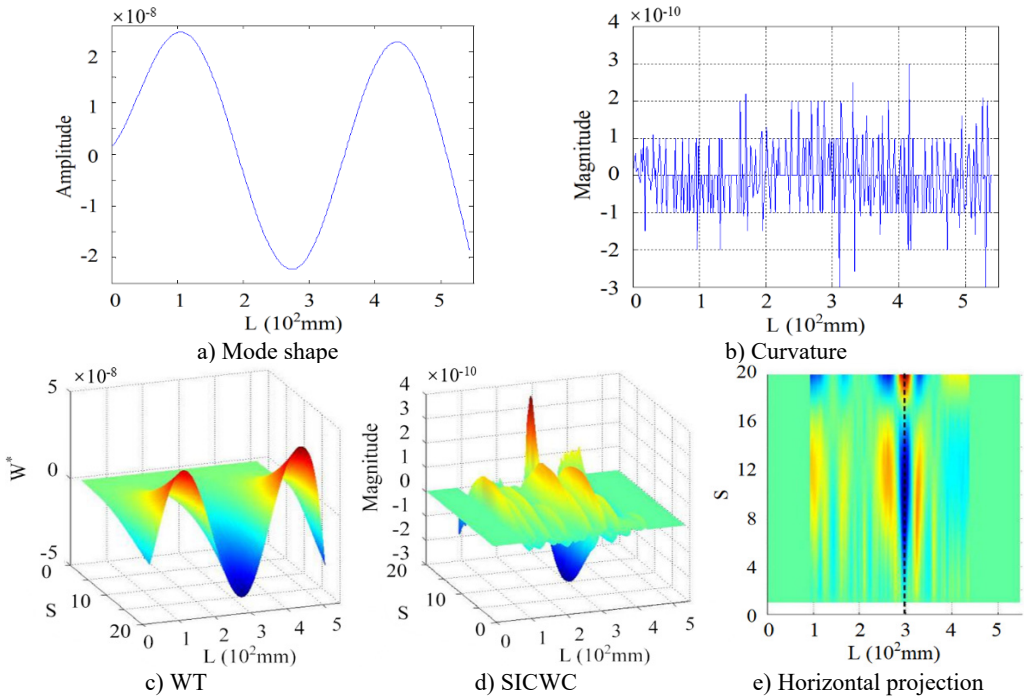


Fig. 26. Experimental detection of the cantilever beam's 4th order mode

This section further elucidates the damage identification performance of the proposed SICWC indicator using two representative mode shapes: a lower-order mode (4th order) and a higher-order mode (7th order) as illustrative examples. Fig. 26(a) displays the 4th mode shape at its natural

frequency, with the corresponding curvature and WT shown in Figs. 26(b) and (c), respectively. While the modal curvature contains multiple high-magnitude singular peaks-potentially leading to false damage detection – the WT mode shape fails to provide definitive damage indication. In contrast, the SICWC in Figs. 26(d) and (e) exhibits a sharp, distinct peak that accurately locates the crack at 296 mm from the fixed end, closely matching the actual crack position at 293 mm.

As shown in Fig. 27, an even clearer detection result is observed in the 7th mode shape, where the SICWC produces a more pronounced singular peak, further confirming the crack's presence. These findings are consistent across most other mode shapes, validating the effectiveness of the SICWC indicator for crack detection in the aluminum beam.

The experimental results demonstrate that measured mode shapes in practical applications inevitably contain noise. Consequently, direct utilization of modal curvature for damage identification proves challenging, while the WT of mode shapes exhibits limited sensitivity to damage. The proposed SICWC effectively enhances damage visibility while suppressing noise interference. It should be emphasized that not all mode orders demonstrate equal damage sensitivity, and practical applications require comprehensive evaluation of multiple modal orders. Particular emphasis should be placed on acquiring higher-order modal results to enhance the reliability of the identification methodology.

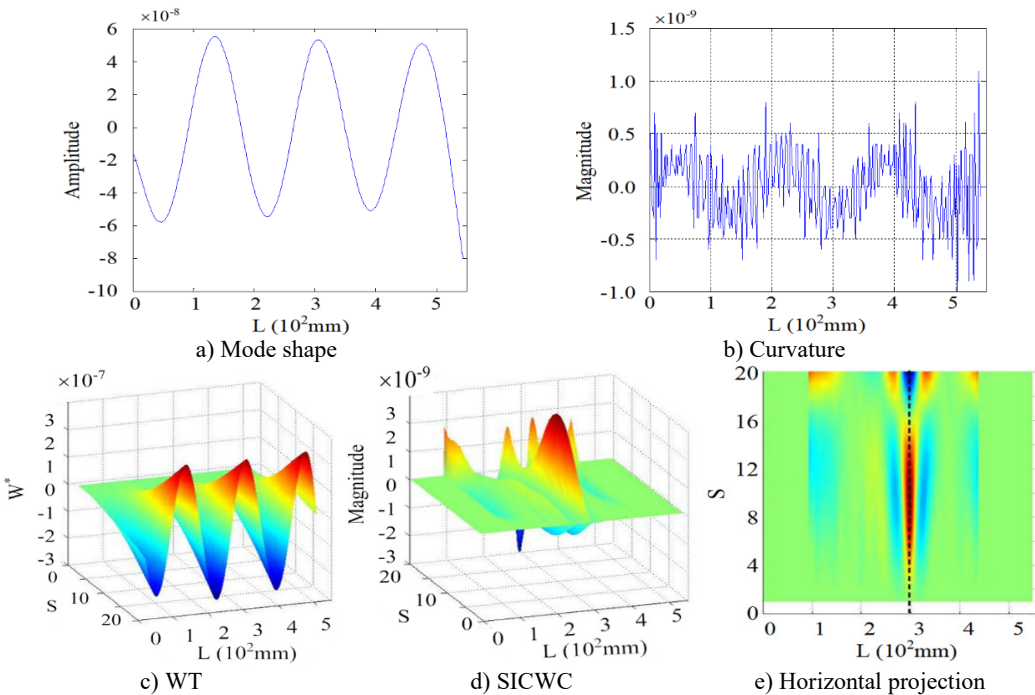


Fig. 27. Experimental detection of the cantilever beam's 7th order mode

5. Conclusions

Modal curvature is widely used as a dynamic indicator for damage identification. However, this method suffers from a critical drawback: extreme sensitivity to noise, which severely undermines its reliability in real-world, noisy environments. To address this limitation, this study proposes a novel damage indicator – the SICWC of mode shapes – which offers two key advantages: enhanced damage sensitivity and robust noise resistance. Numerical simulations of a cracked cantilever beam systematically compare the proposed SICWC with conventional modal curvature, demonstrating its superior performance. Experimental validation on an aluminum beam

with a minor crack further confirms the practical applicability of the SICWC. A critical feature of the SICWC lies in the formulation of the WT mode shape, which enables multiscale analysis of modal characteristics. The SICWC provides a clearer and more accurate damage information by effectively suppressing noise disturbances and isolate damage-related features.

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Data availability

The datasets generated during and/or analyzed during the current study are available from the corresponding author on reasonable request.

Author contributions

Shuigen Hu: investigation, methodology, writing-original draft. Zhichun Ding: investigation, data curation, writing-original draft. Shuping Liu: data curation, writing-review and editing. Qingyang Wei: validation, writing-review and editing. Drahomír Novák: supervision, methodology, writing-review and editing. Maosen Cao: supervision, methodology, writing-review and editing.

Conflict of interest

The authors declare that they have no conflict of interest.

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